

## Scott Mayberry

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RESEARCH INTERESTS Distributed Sensor Fusion, Open-Source Aquatic Robotics, Underwater Communication

EDUCATION **Georgia Institute of Technology**, Atlanta, GA, USA  
Ph.D., Robotics, Expected Jan 2025  
Lab: Georgia Tech Systems Research Laboratory, GTSR  
Advisor: Fumin Zhang, Ph.D

**Massachusetts Institute of Technology**, Cambridge, MA, USA  
B.S., Department of Mechanical Engineering, June 2018

RESEARCH EXPERIENCE **Graduate Research Assistant** Sep 2020 - Present  
Georgia Tech Systems Research Laboratory,  
Georgia Institute of Technology  
Supervisor: Fumin Zhang, Ph.D.  
**Robotics Research Engineer** Sep 2018 - Sep 2020  
Advanced Robotics and Analytics,  
Ford Motor Company  
Supervisor: Raj Sohmshetty  
**Undergraduate Research Assistant** Sep 2016 - May 2017  
Global Engineering and Research Lab,  
Massachusetts Institute of Technology  
Supervisor: Amos Winter, Ph.D.

FELLOWSHIP **National Science Foundation Graduate Research Fellow (NSF GRFP)**

PUBLICATIONS

1. Zhang, Z., **Mayberry, S.**, Wu, W., & Zhang, F. (2023). Distributed cooperative Kalman filter constrained by advection–diffusion equation for mobile sensor networks. *Frontiers in Robotics and AI*, 10.
2. Zhang, Z., **Mayberry, S.**, Wu, W., & Zhang, F. (2023). Distributed Cooperative Kalman Filter Constrained by Discretized Poisson Equation for Mobile Sensor Networks. *2023 American Control Conference (ACC)*, 1365–1370.
3. **Mayberry, S.**, Wang, J., Tao, Q., Zhang, F., Song, A., Hong, X., Dong, S., Webb, C., Dugaev, D., & Peng, Z. (2021). First Step Towards  $\mu$ Net: Open-Access Aquatic Testbeds and Robotic Ecosystem. *The 15th International Conference on Underwater Networks & Systems*, 1–8.
4. Cai, J., **Mayberry, S.**, & Zhang, F. (2022). First Step Towards Low-Cost, Open-Source Optical Modem for Underwater Communication with Experimental Results. *The 16th International Conference on Underwater Networks & Systems*, 1–2.
5. **Mayberry, S.**, Cai, J., & Zhang, F. (2022). BlueBuzz, an Open-Source Acoustic Modem. *OCEANS 2022, Hampton Roads*, 1–7.
6. Ramachandran, B., **Mayberry, S.**, & Zhang, F. (2023). Acoustic Localization of Underwater Robots: A Time of Arrival-Based Particle Filter Approach Using Asynchronous Beacon Pinging. *2023 8th International Conference on Automation, Control and Robotics Engineering (CACRE)*, 294–299.

## PATENTS

1. **S. Mayberry**, R. Sohmshtetty, & S. Hoff, "Decentralized Location Determination Systems and Methods," U.S. Patent 11,417,015 B2, Aug. 16, 2022
2. R. Roychowdhury, D. J. Berels, M. Y. Ghannam, & **S. Mayberry**, "System and Method for Circuit Testing Using Remote Cooperative Devices," U.S. Patent 11,592,468 B2, Feb. 28, 2023.
3. Y. Chen, R. Somshekar, J. Lu, & **S. Mayberry**, "Smartphone and Battery Integration Module for an Electric Scooter," U.S. Patent 11,812,151 B2, Nov. 7, 2023.
4. **S. Mayberry**, D. Berels, M. Y. Ghannam, & R. Roychowdhury, "Dead Reckoning Correction Utilizing Patterned Light Projection," U.S. Patent 11,662,208 B2, May 30, 2023
5. D. J. Berels, J. Engels, **S. Mayberry**, G. K. Thomas, & M. V. Volpone, "Motor Vehicle Floor Assembly with Recesses for Electrical Lines and Electrical Modules," U.S. Patent 11,364,956 B2, Jun. 21, 2022

## PATENTS PENDING

1. **S. Mayberry**, "Systems and Methods for Predicting Travel Destination of an Automobile Based on Attire Worn by Individual," U.S. Patent Application Pub. No. US 2020/0249046 A1, Aug. 6, 2020
2. **S. Mayberry** & R. Sohmshtetty, "Stackable Battery Assemblies and Methods of Use," U.S. Patent Application Pub. No. US 2022/0007526 A1, Jan. 6, 2022
3. R. Sohmshtetty, V. Rajendra, & **S. Mayberry**, "Systems and Methods for Ensuring Privacy in an Autonomous Vehicle," U.S. Patent Application Pub. No. US 2022/0253550 A1, Aug. 11, 2022
4. D. J. Berels, M. Y. Ghannam, R. Roychowdhury, & **S. Mayberry**, "Independent Conductive Tape Dispensing System for Manufacturing of Electrical Distribution Circuits in Vehicles," U.S. Patent Application Pub. No. US 2022/0097317 A1, Mar. 31, 2022
5. R. Sohmshtetty, **S. Mayberry**, V. Rajendra, & S. Hoff, "Stand-Alone Inspection Apparatus for Use in a Manufacturing Facility," U.S. Patent Application Pub. No. US 2022/0136872 A1, May 5, 2022
6. R. Roychowdhury, D. J. Berels, M. Y. Ghannam, & **S. Mayberry**, "System and Method for Circuit Testing Using Remote Cooperative Devices," U.S. Patent Application Pub. No. US 2023/0194586 A1, Jun. 22, 2023

## HARDWARE

### **Miniature Underwater Robot (MUR)**

Open-source underwater robot with custom controller, custom power management system, and ML capabilities.

### **BlueBuzz Acoustic Modem**

Open-source acoustic modem for underwater communication.

### **Multi-Use Autonomous Robot for People and Material Transport**

Person and material transport robot that can navigate autonomously, load and unload packages, and transport people. Contributions include electrical, software, and mechanical design and implementation.

### **Autonomous Wall Unit for Material Storage and Management**

Wall unit that can communicate with robotic infrastructure to autonomously accept, store, and deliver packages. Contributions include electrical, software, and mechanical design and implementation.

AWARDS	<b>Ford Recognition Award</b>	Aug 2019
	For exemplary diligence and team work	
	<b>Ford Recognition Award</b>	July 2020
	For design and implementation of in-plant material delivery robot	
	<b>Academic All-American</b>	May 2015
	MIT Swimming	
TEACHING EXPERIENCE	<b>Teaching Assistant</b>	Spring 2021-Present
	Georgia Tech Vertically Integrated Projects Instructor: Fumin Zhang, Ph.D Georgia Institute of Technology	
	<b>Project Team Leader</b>	Spring 2017 - Fall 2017
	Design and Implementation of Hydrogen ICE (HICE) Instructor: Douglas Hart, Ph.D Massachusetts Institute of Technology	
REFERENCES	Fumin Zhang, Professor	
	School of Electrical and Computer Engineering, Georgia Institute of Technology	Phone: 404-385-2751 E-mail: fumin@gatech.edu
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	Advanced Robotics and Analytics, Ford Motor Company	Phone: 734-507-0353 E-mail: rsohmshe@ford.com
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